

# Why experimenters might not always want to randomize, and what they could do instead

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## Setup

- **Sampling:**  
random sample of  $n$  units  
baseline survey  $\Rightarrow$  vector of covariates  $X_i$
- **Treatment assignment:**  
binary treatment assigned by  $D_i = d_i(X, U)$   
 $X$  matrix of covariates;  $U$  randomization device
- **Realization of outcomes:**  
 $Y_i = D_i Y_i^1 + (1 - D_i) Y_i^0$
- **Estimation:**  
estimator  $\hat{\beta}$  of the (conditional) average treatment effect,  $\beta = \frac{1}{n} \sum_i E[Y_i^1 - Y_i^0 | X_i, \theta]$

## Questions

- How should we assign treatment?
- In particular, if  $X$  has continuous or many discrete components?
- How should we estimate  $\beta$ ?
- What is the role of prior information?

## Some intuition

- "Compare apples with apples"  
 $\Rightarrow$  balance covariate distribution.
- Not just balance of means!
- We don't add random noise to estimators  
– why add random noise to experimental designs?
- Identification requires controlled trials (CTs), but not randomized controlled trials (RCTs).

## Framework

- **Decision theoretic:**  
 $\mathbf{d}$  and  $\hat{\beta}$  minimize risk  $R(\mathbf{d}, \hat{\beta} | X)$   
(e.g., expected squared error)
- **Nonparametric:**  
no functional form assumptions
- **Bayesian or minimax**

## Main results

- The unique optimal treatment assignment does not involve randomization.
- Identification using conditional independence is still guaranteed without randomization.
- Tractable nonparametric priors  
 $\Rightarrow$  Explicit expressions for risk as a function of treatment assignment  
 $\Rightarrow$  choose  $\mathbf{d}$  to minimize these

## A formal decision problem

- Risk function of treatment assignment  $\mathbf{d}(X, U)$ , estimator  $\hat{\beta}$ , for loss  $L$ , data generating process  $\theta$ :

$$R(\mathbf{d}, \hat{\beta} | X, U, \theta) := E[L(\hat{\beta}, \beta) | X, U, \theta]$$

- (Conditional) Bayesian risk:

$$R^B(\mathbf{d}, \hat{\beta} | X, U) := \int R(\mathbf{d}, \hat{\beta} | X, U, \theta) dP(\theta)$$

- Conditional minimax risk:

$$R^{mm}(\mathbf{d}, \hat{\beta} | X, U) := \max_{\theta} R(\mathbf{d}, \hat{\beta} | X, U, \theta)$$

- Objective:  $\min R^B$  or  $\min R^{mm}$

## Theorem (Optimality of deterministic decisions)

Consider a general decision problem.

Let  $R^*$  equal  $R^B$  or  $R^{mm}$ . Then:

- The optimal risk  $R^*(\delta^*)$ , when considering only deterministic procedures  $\delta(X)$ , is no larger than the optimal risk when allowing for randomized procedures  $\delta(X, U)$ .
- If the optimal deterministic procedure  $\delta^*$  is unique, then it has strictly lower risk than any non-trivial randomized procedure.

## Numerical example

- Covariates:  $(x_1, \dots, x_4) = (0, 1, 2, 3)$
- Model 1:  $Y_i^d = x_i + d + \epsilon_i^d$
- Model 2:  $Y_i^d = -x_i^2 + d + \epsilon_i^d$
- Prior over models (covariance kernel for  $f$ ):  
 $C((x_1, d_1), (x_2, d_2)) = 10 \cdot \exp(-(\|x_1 - x_2\|^2 - (d_1 - d_2)^2) / 10)$

Table:

- One row for each non-random treatment assignment  $(d_1, \dots, d_4)$
- Randomized designs: Assign equal probability to all assignments  $(d_1, \dots, d_4)$  marked by "1"
- Bias, Variance, and MSE for difference-in-means estimator, under either model, and integrating over prior
- MSE for random designs: average of non-random MSEs

assignment	designs					model 1			model 2			EMSE
$d_1$ $d_2$ $d_3$ $d_4$	1	2	3	4	5	bias	var	MSE	bias	var	MSE	
0 1 1 0 0	1	1	1	1	1	0.0	1.0	1.0	2.0	1.0	5.0	1.77
1 0 0 1 0	1	1	1	1	1	0.0	1.0	1.0	-2.0	1.0	5.0	1.77
1 0 1 0 1	1	1	1	1	0	-1.0	1.0	2.0	3.0	1.0	10.0	2.05
0 1 0 1 1	1	1	1	1	0	1.0	1.0	2.0	-3.0	1.0	10.0	2.05
1 1 0 0 0	1	1	1	0	0	-2.0	1.0	5.0	6.0	1.0	37.0	6.51
0 0 1 1 1	1	1	1	0	0	2.0	1.0	5.0	-6.0	1.0	37.0	6.51
0 1 0 0 0	1	1	0	0	0	-0.7	1.3	1.8	3.3	1.3	12.4	2.49
0 0 1 0 0	1	1	0	0	0	0.7	1.3	1.8	-0.7	1.3	1.8	2.49
1 1 0 1 1	1	1	0	0	0	-0.7	1.3	1.8	0.7	1.3	1.8	2.49
1 0 1 1 1	1	1	0	0	0	0.7	1.3	1.8	-3.3	1.3	12.4	2.49
1 0 0 0 0	1	1	0	0	0	-2.0	1.3	5.3	4.7	1.3	23.1	6.77
1 1 1 0 0	1	1	0	0	0	-2.0	1.3	5.3	7.3	1.3	55.1	6.77
0 0 0 1 1	1	1	0	0	0	2.0	1.3	5.3	-7.3	1.3	55.1	6.77
0 1 1 1 1	1	1	0	0	0	2.0	1.3	5.3	4.7	1.3	23.1	6.77
0 0 0 0 0	1	0	0	0	0	-	-	-	-	-	-	-
1 1 1 1 1	1	0	0	0	0	-	-	-	-	-	-	-
MSE model 1:	$\infty$	3.2	2.7	1.5	1.0							
MSE model 2:	$\infty$	20.6	17.3	7.5	5.0							

## Nonparametric Bayesian setup

- Prior moments:  
 $f(x, d) := E[Y_i | X_i = x, D_i = d]$   
 $\text{Cov}(f(x_1, d_1), f(x_2, d_2)) = C((x_1, d_1), (x_2, d_2))$   
 $\mu_i = E[Y_i | X, D]$ ,  $\mu_\beta = E[\beta | X, D]$   
 $\Sigma = \text{Var}(Y | X, D, \theta)$   
 $C_{i,j} = C((X_i, D_i), (X_j, D_j))$  and  $\bar{C}_i = \text{Cov}(Y_i, \beta | X, D)$ .
- Mean squared error objective:  
Loss  $L(\hat{\beta}, \beta) = (\hat{\beta} - \beta)^2$ ,  
Bayes risk  $R^B(\mathbf{d}, \hat{\beta} | X) = E[(\hat{\beta} - \beta)^2 | X]$ .
- Linear estimators:  
 $\hat{\beta} = w_0 + \sum_i w_i Y_i$ .

## Theorem (Best linear predictor, posterior variance)

The optimal estimator is

$$\hat{\beta} = \mu_\beta + \bar{C}' \cdot (C + \Sigma)^{-1} \cdot (Y - \mu),$$

and the corresponding expected loss (risk) is

$$R^B(\mathbf{d}, \hat{\beta} | X) = \text{Var}(\beta | X) - \bar{C}' \cdot (C + \Sigma)^{-1} \cdot \bar{C}.$$

## Discrete optimization

- The optimal design solves  
$$\max_{\mathbf{d}} \bar{C}' \cdot (C + \Sigma)^{-1} \cdot \bar{C}.$$
- Possible minimization algorithms: Search over random  $\mathbf{d}$ ; greedy algorithm; simulated annealing

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